AKSYNC Communications	@AKSYNC_ACTIONS

Specify when to send an AKSYNC command failure.

Keyword:

@AKSYNC_ACTIONS

Usage:

This keyword is used to specify the actions and timing associated with all AKSYNC communications for a test mode. The `start_type` specifies when the commands will be executed, the `stop_path` specifies what action will be taken when all commands have been completed, and the `fail_path` specifies what to do if the communication fails to complete successfully.

Data Fields:

start_type	code for when to send the message - options are AT_START, AFTER_STABILITY, AT_END
stop_path	code for what action to take when the communication is complete - options are NONE, MODE_TERMINATE, RETURN, a mode number, or a procedure file pathname.
fail_path	code for what action to take if there is a failure to communicate with the ECM - options include NONE, MODE_TERMINATE, RETURN, a mode number, or a procedure file pathname.

Example Specification:

```
@AKSYNC_ACTIONS
        #start_type stop_path           fail_path
        AT_START    MODE_TERMINATE      /specs/gp/comm_fail
```

Start sending the AKSYNC commands at the start of the mode, terminate the mode when all are complete, and if there is a failure, go to the test mode specified by the `@ELSE_MODE` keyword.

Notes:

This keyword is used only when there are other AKSYNC communication commands such as `@AKSYNC`.