Smart Device Communications	@DEVCOM_ACTIONS

Command used to communicate with a device supporting the AK protocol.

Keyword:

@DEVCOM_ACTIONS

Usage:

Data Fields:

start_code	code for when to send the command - options are AT_START or AFTER_STABILITY - default is AT_START
success_path	code for what action to take when communication is complete - options are NONE, MODE_TERMINATE, RETURN, a mode number, or a procedure file pathname - default is NONE
fail_path	code for what action to take if communication fails - options are NONE, MODE_TERMINATE, RETURN, a mode number, or a procedure file pathname - default is NONE

Example Specification:

```
@DEVCOM_ACTIONS
        #start_code     success_path    fail_path
        AT_START        MODE_TERMINATE /specs/gp/quit
```